

NAME

smthread_t – SSM Thread Class

SYNOPSIS

```

#include <sm_vas.h> // which includes smthread.h

typedef void st_proc_t(void *);

class smthread_t : public sthread_t {
public:
    NORET          smthread_t(
        st_proc_t*      f,
        void*           arg,
        priority_t      priority = t_regular,
        bool            block_immediate = false,
        bool            auto_delete = false,
        const char*     name = 0,
        long            lockto = WAIT_FOREVER);

    NORET          smthread_t(
        priority_t      priority = t_regular,
        bool            block_immediate = false,
        bool            auto_delete = false,
        const char*     name = 0,
        long            lockto = WAIT_FOREVER);

    NORET          ~smthread_t();

    virtual void    run() = 0;

    void            attach_xct(xct_t* x);
    void            detach_xct(xct_t* x);
    xct_t*          xct();
    const xct_t*    const_xct() const;
    static smthread_t* me();

    // set and get lock_timeout value
    long            lock_timeout() const;
    void            lock_timeout(long i);

    /*
     * These methods are used to verify than nothing is
     * left pinned accidentally. Call mark_pin_count before an
     * operation and check_pin_count after it with the expected
     * number of pins that should not have been released.
     */
    void            mark_pin_count();
    void            check_pin_count(int change);
    void            check_actual_pin_count(int actual) ;
    void            incr_pin_count(int amount) ;

    /*
     * These methods are used to verify that a thread

```

```

        * is only in one ss_m::, scan::, or pin:: function at a time.
        */
    void                in_sm(bool in);
    bool                is_in_sm() const;

private:
    void                user(); /* disabled sthread_t::user */
};

```

DESCRIPTION

Class **smthread_t** inherits from **sthread_t**, and extends it for use by the higher layers of the Shore Storage Manager. Any thread calling methods documented in *ssm* section manual pages (see **intro(ssm)** for a list) must be an **smthread_t** or derived from it.

sthread_t(priority, block_immediate, auto_delete, name, lock_timeout)

See **sthread_t(sthread)** for details on the *priority*, *block_immediate*, *auto_delete* and *name* parameters. The *lock_timeout* parameter specifies the default for how long a lock request by the smthread should block before it times out.

run()

This method is the body of the thread. See **sthread_t(sthread)** for more details. Users must provide their own **run** method.

Methods pertinent to Transactions

Threads often run on behalf of a transaction, so there are methods for associating a thread with a transaction. For more information on transactions, see **transaction(ssm)**

attach_xct(xct)

The **attach_xct** method attaches the thread to transaction *xct*. Any SSM operation, performed by this thread, that requires transaction information will use the *xct* transaction. For example, all locks acquired by operations will be for the *xct* transaction. The **ss_m::begin_xct** method automatically calls **attach_xct**. It is a fatal error to call **attach_xct** if the thread is already attached to a transaction.

More than one thread can operate on behalf of a given transaction at any time, but certain transaction-related activities are serialized with a synchronization variable. For example, only one of the threads can be writing log records for a top-level (compensated) operation at any time. Another example of such serialization involves the lock manager: if any single thread of a multi-threaded transaction waits on a lock, all of the transaction's threads that would block in the lock manager wait on the same lock (regardless what locks they are trying to acquire).

A VAS that attaches a transaction to more than one thread runs a high risk of getting latch-latch deadlocks among threads. It is the responsibility of the VAS to implement its own protocol for avoiding these deadlocks. An example of such a protocol is to allow threads of multi-threaded transactions to work on non-overlapping partitions of the database.

It is also the responsibility of the VAS to see that certain operations, including commit and abort, are not attempted while a transaction is attached to several threads.

detach_xct(xct)

The **detach_xct** method detaches the thread from transaction *xct*. It is a fatal error if the thread is not already attached to *xct*.

xct()

The **xct** method returns the transaction to which the thread is currently attached.

ERRORS

TODO

EXAMPLES

See **Writing Value-Added Servers with the Shore Storage Manager** for an example of how to use threads in a server.

VERSION

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SEE ALSO

intro(sthread) sthread_t(sthread) transaction(ssm) lock(ssm)