# Fall 1995 Qualifier Exam: MATHEMATICAL PROGRAMMING 

Instructions: Answer 5 of the following 7 questions.

1. Solve the following linear program

$$
\begin{array}{ll}
\max & x_{1}-x_{2}+7 \\
\text { s.t. } & x_{1}+4 x_{2}=5 \\
& x_{1}-3 x_{2}+x_{3}=7 \\
& x_{1}+x_{2}-x_{3} \leq 8 \\
& x_{1} \leq 1, \quad x_{3} \geq 0
\end{array}
$$

2. Show that any solvable linear program has a strictly complementary solution. (You may wish to consider the linear program

$$
\begin{array}{ll}
\max & \epsilon \\
\text { s.t. } & A x \geq b \\
& c \geq A^{T} u \\
& b^{T} u \geq c^{T} x \\
& u+A x-b \geq \epsilon 1_{m} \\
& x+c-A^{T} u \geq \epsilon 1_{n} \\
& x, u \geq 0
\end{array}
$$

where $1_{m}$ and $1_{n}$ are appropriately dimensioned vectors of 1 's.)
3. Consider the nonlinear program

$$
\min _{x} f(x) \quad \text { s.t. } g(x) \leq 0
$$

where $f: R^{n} \rightarrow R, \quad g: R^{n} \rightarrow R^{m}$, are differentiable functions on $R^{n}$. Suppose that a linearization of the problem at some feasible point $\bar{x}$ has no strict feasible descent direction, that is the following linearized system has no solution in $x$ :

$$
\begin{gathered}
f(\bar{x})+\nabla f(\bar{x})(x-\bar{x})<f(\bar{x}) \\
g_{I}(\bar{x})+\nabla g_{I}(\bar{x})(x-\bar{x})<g_{I}(\bar{x})=0,
\end{gathered}
$$

where $I:=\left\{i \mid g_{i}(\bar{x})=0\right\}$.
(a) What optimality conditions are satisfied at $\bar{x}$ ? Justify.
(b) What additional assumptions on $\nabla g_{I}(\bar{x})$ can strengthen these optimality conditions? Justify.
Hint The Gordan Theorem may be useful in answering both (a) and (b).
4. Consider the nonlinear program $\min _{x \in X} f(x)$, where $f: R^{n} \rightarrow R$ and $X$ is a subset of $R^{n}$. Define the exterior penalty function:

$$
P(x, \alpha):=f(x)+\alpha \beta(x),
$$

where $\beta$ : $R^{n} \rightarrow R$ such that $\beta(x)=0$ on $X$, else $\beta(x)>0$. Let $\alpha_{2}>\alpha_{1}>0$, and

$$
x^{i} \in \underset{x \in R^{n}}{\arg \min } P\left(x, \alpha_{i}\right), \quad i=1,2 .
$$

(a) Show that $f\left(x^{i}\right) \leq \inf _{x \in X} f(x)$.
(b) $f\left(x^{2}\right) \geq f\left(x^{1}\right)$.
(c) Suppose that you are given an arbitrary $x^{0} \in X$, and that you have computed $x^{1}$ for some $\alpha_{1}>0$. How would you choose $\alpha_{2}$ so that $\beta\left(x^{2}\right)<\delta$ for some given infeasibility tolerance $\delta>0$ ?
5. Suppose $f$ is a proper convex function on $\mathbf{R}^{n}$. Assume that for some nonzero $y^{*} \in \mathbf{R}^{n}$ and $\alpha^{*} \in \mathbf{R}$, and for all $x \in \mathbf{R}^{n}$, either $f(x)=+\infty$ or $\left\langle y^{*}, x\right\rangle \leq \alpha^{*}$. Let $x^{*} \in \operatorname{dom} f^{*}$ and consider the halfline from $x^{*}$ in the direction of $y^{*}$. Exhibit the least value of $\alpha$ such that for each $t \geq 0$,

$$
f^{*}\left(x^{*}+t y^{*}\right) \leq f^{*}\left(x^{*}\right)+t \alpha .
$$

You must prove that (i) the bound holds for your $\alpha$, and (ii) your $\alpha$ is the best possible without more information on $f$. (You may find it useful to look at the support function of $\operatorname{dom} f$.)
6. Consider the nonlinear integer program:

$$
(N I P) \quad \min _{x} 1-x_{1} x_{2} \quad \text { s.t. } \quad A x \leq b, \quad x \geq 0, \quad x \text { integer }
$$

a) Assuming that the constraints imply $x_{1} \leq 1$ and $x_{2} \leq 1$, formulate this problem as a linear integer program and explain why your formulation is an equivalent problem.
Now suppose that $A x \leq b$ is the single constraint $x_{1}+x_{2} \leq 1$.
b) What is the optimal solution and optimal value of the corresponding nonlinear integer program?
c) Consider an arbitrary linear integer program (not simply the one developed in part a) ) that is equivalent to (NIP), assuming only that the constraints $A x \leq b$ imply $x_{1} \leq 1$ and $x_{2} \leq 1$. Show that the LP relaxation of this arbitrary equivalent linear integer program will have optimal value not greater than $1 / 2$ when the constraints $A x \leq b$ are specified to be $x_{1}+x_{2} \leq 1$. (Hint: use convexity properties of LP).
7. Consider a network flow problem with $n$ nodes:

$$
\min _{x} \quad c x \quad \text { s.t. } \quad A x=b, \quad x \geq 0
$$

where c is a vector all of whose components are 1 in absolute value.
Suppose the dual solution $\pi$ (not necessarily dual feasible) satisfies the usual complementarity conditions with respect to a primal feasible solution defined on a spanning tree T .
a) If $\pi_{n}=0$, derive a bound for $\pi_{1}$ in terms of the problem data, and state necessary and sufficient conditions under which this bound will be attained.
b) If no assumptions are made on the value of any $\pi_{i}$, can a bound still be derived for $\pi_{1}$ from the complementarity conditions for this problem? Explain your answer.

