

**NAME**

scan\_index\_i – Class for Scanning B+tree Indexes

**SYNOPSIS**

```
#include <sm_vas.h> // which includes scan.h

class scan_index_i {
public:
    enum cmp_t { bad_cmp_t=badOp, eq=eqOp,
                  gt=gtOp, ge=geOp, lt=ltOp, le=leOp };

    /* Logical-ID version */
    NORET          scan_index_i(
        const lvid_t&           lvid,
        const serial_t&         stid,
        cmp_t                 c1,
        const cvec_t&           bound1,
        cmp_t                 c2,
        const cvec_t&           bound2,
        concurrency_t          cc = t_cc_kvl);

    /* Physical-ID version */
    NORET          scan_index_i(
        const stid_t&           stid,
        cmp_t                 c1,
        const cvec_t&           bound1,
        cmp_t                 c2,
        const cvec_t&           bound2,
        concurrency_t          cc = t_cc_kvl);

    NORET          ~scan_index_i();

    rc_t           curr(
        vec_t*                key,
        smsize_t&             klen,
        vec_t*                el,
        smsize_t&             elen);

    rc_t           next(bool& eof)

    void          finish();
    bool          eof();
    rc_t          error_code();
};

}
```

**DESCRIPTION**

Class **scan\_index\_i** supports scanning a range in a B+ tree index. The scan is controlled by a **scan\_index\_i** object. Multiple scans can be open at one time. More information on indexes and key types is can be found in the **SSM interface document**.

**scan\_index\_i(lvid, stid, c1, bound1, c2, bound2, cc)**

The **scan\_index\_i** constructor is used to initialize a scan. The *lvid* and *stid* parameters specify the index to be scanned. The *bound1* and *bound2* parameters specify the keys marking the beginning and end of the scan, respectively. The *c1* and *c2* parameters specify how comparisons should be made with their corresponding bounds. Valid values are:

- eq:** Only keys equal to the bound will be returned.  
Valid for *c1* or *c2*.
- gt:** Only keys greater than the bound will be returned.  
Valid only for *c1*.
- ge:** Only keys greater than or equal to the bound will be returned. Valid only for *c1*.
- lt:** Only keys less than the bound will be returned.  
Valid only for *c2*.
- le:** Only keys less than or equal to the bound will be returned. Valid only for *c2*.

The *cc* parameter specifies the granularity of locks acquired for concurrency control. See **enum(ssm)** for a description of the values. Here are the effects of all valid values for file scan:

**t\_cc\_none:**

The file is IS locked, but no locks are obtained on any pages or entries in the file.

**t\_cc\_kvl:**

The file is IS locked and the keys of the index entries are locked. Next-key locking provides phantom protection.

**t\_cc\_modkvl:**

The file is IS locked and the keys of the index entries are locked. No next-key locking is done. The only permissible scans are those where both bounds are **eq**.

**t\_cc\_im:**

The value in an entry is treated as a (physical) record identifier, and that record's lock is obtained. Next-record locking provides phantom protection. This locking protocol not useful for VASs that use logical identifiers.

**t\_cc\_file:**

The file is SH locked, so no finer-granularity locks are obtained.

**~scan\_index\_i()**

The destructor frees all resources used by the scan.

**curr(key, klen, el, elen)**

The **curr** method copies out the current key and element. They are copied to the memory addressed by the *key* and *el* vectors. The *klen* parameter will be set to the length of the key copied out. The *elen* parameter will be set to the length of the element copied out.

**next\_eof()**

The **next** method advances the scan to the next key/element pair. If the upper bound of the scan has been reached, *eof* will be set to **true**.

**finish()**

The **finish** method frees all resources used by the scan.

**eof()**

If the upper bound of the scan has been reached, the **eof** method will return **true**.

**error\_code()**

The **error\_code** method will return any error code generated by the other scan member methods. For more information on errors, see ERRORS section below.

**Updates While Scanning**

A common question is *what is the effect of changes to an index made by a transaction that is also scanning the index?* It is not safe to change anything in the file while scanning. Instead, a list of changes should be made during the scan and only performed after the scan is complete.

**ERRORS**

A **scan\_index\_i** object remembers if an error has occurred while constructing the scan or while scanning. An error that occurs in constructing the scan (such as having a bad index ID), can be detected by calling **error\_code**. Alternatively, the error can be detected on the first call to **next** which will return the remembered error code. Therefore, if an error occurs while constructing or scanning, repeated calls to **next** will all return the first error code and no progress will be made on the scan.

**EXAMPLES**

To Do.

**VERSION**

This manual page applies to Version 2.0 of the Shore Storage Manager.

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**SEE ALSO**

**intro(ssm)**, **btree(ssm)**, **scan\_file\_i(ssm)**, **scan\_rt\_i(ssm)**